

Algorithm Closest_pair(PX, n)

//Input: An array PX[0 .. n-1] of points, and parameter n, size of the array. Each cell PX[i] has 3 components:
PX[i] = { PX[i].ID, PX[i].x, PX[i].y }: the ID, x and y coordinate of point PX[i]
The points in PX are sorted (ascending order) according to the x coordinate

//Output: min_dist: minimum distant between two points in PX
PY[0 .. n-1]: Points in PX now sorted (ascending order) according to the y coordinate

//check the base case

If n = 1 return (INF, PX)

If n = 2

min_dist \leftarrow dist(PX[0], PX[1])

If PX[0].y \leq PX[1].y

PY[0] \leftarrow PX[0]

PY[1] \leftarrow PX[1]

Else PY[0] \leftarrow PX[1]

PY[1] \leftarrow PX[0]

Return (min_dist, PY)

//Divide into two subproblems

mid \leftarrow n/2

PXL \leftarrow PX[0..mid-1]

PXR \leftarrow PX[mid .. n-1]

// Conquer the subproblems

(dL, PYL) \leftarrow Closest_pair(PXL, mid) // the left half of the points

// PYL is the array of points in PXL sorted by y coordinate

(dR, PYR) \leftarrow Closest_pair(PXR, n-mid) // the right half of the points

// PYR is the array of points in PXR sorted by y coordinate

//Combine the solutions for the subproblems

d \leftarrow min (dL, dR) // d is the current minimum distance

PY \leftarrow merge (PYL, PYR) // PY is the array of points in PX sorted by the y coordinate

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// The merge method is essentially the same as in merge sort

mid_x ← PX[mid].x           // the x value of the split point

length ← 0
i ← 0

While (i ≤ n-1) Do

    If | PY[i].x - mid_x | ≤ d

        Strip[length] ← PY[i]    // point PY[i] is within the strip of width 2d centered around
                                   // the line x = mid_x
        length ← length + 1

    i ← i+1

    // Now the array Strip contains all points in PY which are within
    // the strip of width 2d centered around the line x = mid_x

    //The number of elements in Strip is length

min_dist ← d

    //Next we will check the points in Strip for possible smaller
    // distance than min_dist

For i ← 0 to length-2 Do

    k ← i+1           // Only check points in Strip with index larger than i

    While (k ≤ length-1 AND Strip[k].y - Strip[i].y ≤ d) Do

        new_d ← dist(Strip[i], Strip[k])
        min_dist ← min(d, new_d)    // update the current min_dist

Return (min_dist, PY)
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